

Azure RTOS and Microchip ATSAME54-XPro Evaluation kit

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There are a number of Azure RTOS online guides to get started with different platforms. The ATSAME54-XPRO is one of the first platforms that demonstrated connecting to Azure IoT Central. If you follow the <u>quick start online documents</u>, you will be able to build the example application from the command line and get it to run. If you want to use the example application as a basis for a project, being able to debug by stepping through the code is going to be important. In this paper, we will walk through the example but set up the development environment to use Visual Studio Code.

Target Hardware: SAM E54 XPLAINED PRO EVALUATION KIT (ATSAME54-XPRO).

1 Tools Setup

For this setup we will need to download and install a few items.

- 1. Download and install Visual Studio Code: Visual Studio Code Code Editing 1.69.2.
- 2. Once Visual Studio Code has been installed, install the following add-ons from the Visual Studio Code marketplace:
 - <u>C/C++ Visual Studio Marketplace</u>
 - <u>CMake Tools Visual Studio Marketplace</u>
 - <u>CMake Visual Studio Marketplace</u>
 - <u>Cortex-Debug Visual Studio Marketplace</u>
 - Embedded Tools Visual Studio Marketplace
- 3. Install Git so we can download the Azure RTOS to get started building the files: <u>Git -</u> <u>Downloads (git-scm.com).</u>
 - a. Accept the license, and click Next.
 - b. Leave the install location as is, and click Next.
 - c. Leave the Selected Components as they are, and click Next.
 - d. Keep the State Menu Folder as is, and click Next.
 - e. Set the default editor selection to be "Use Visual Studio Code as Git's default editor", and click Next.

Cho V	oosing the default editor used l Which editor would you like Git to us	by Git e?		<	8
	Use Visual Studio Code as Git's def	ault editor		~	
	Visual Studio Code is an Open running as a desktop applicatic TypeScript and Node.js and ha languages (such as C++, C#, .NET and Unity). (WARNING!) This will be install Use this option to let Git use Vi	Source, lightweight and p on. It comes with built-in s as a rich ecosystem of ext Java, Python, PHP, Go) a ed only for this user. Isual Studio Code as its de	owerful editor upport for Java ensions for oth and runtimes (su fault editor.	aScript, er uch as	
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- f. Keep the default for initial branches, and click Next.
- g. Keep the default PATH Environment, and click Next.
- h. Keep the default OpenSSH selection, and click Next.
- i. Select "Use Windows' default console window", and click Next.

Use MinTTY (the default terminal of MSYS2) Git Bash will use MinTTY as terminal emulator, which sports a resizable window, non-rectangular selections and a Unicode font. Windows console programs (such as interactive Python) must be launched via `winpty` to work in MinTTY. Use Windows' default console window Git will use the default console window of Windows ('cmd.exe'), which works well with Win32 console programs such as interactive Python or node.js, but has a very limited default scroll-back, needs to be configured to use a Unicode font in order to display non-ASCII characters correctly, and prior to Windows 10 its window was not fredy resizable and it only allowed rectangular text selections.	Configuring the terminal emulator to use Which terminal emulator do you want to use	with Git Bash with your Git Bash	1?	
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- j. Keep the defaults for the next question, and click Next.
- k. Keep the defaults for the next question, and click Next.
- I. Keep the defaults for the next question, and click Next.
- m. Keep the defaults for the extra options, and click Next.
- n. Keep the defaults for the experimental options, and click Install.
- o. Click Finish once the install completes.
- 4. Download and install a serial terminal program such as HyperTerminal, PuTTY, or <u>Annabooks COM Terminal</u>.
- 5. Reboot the computer.

2 Visual Studio Code Sample Application

This section covers the sample Azure RTOS getting-started sample but uses Visual Studio Code to implement the sample.

2.1 Download the Getting Started Files from GitHub

We need to get the getting-started repository that contains the Azure RTOS build example and the ports to the ATSAME54-XPRO and other development kits.

- 1. Create a directory called \Azure-RTOS-Microchip-E54
- 2. Open PowerShell.
- 3. Change the directory to the newly created folder:

cd \Azure-RTOS-Microchip-E54

4. Run the following

git clone --recursive https://github.com/azure-rtos/getting-started.git



2.2 Create Azure IoT Central Application

Now, we need to set up the application on Azure IoT Central.

- 1. In a browser, open https://apps.azureiotcentral.com/home
- 2. Sign into the account or create an account.
- 3. Click on Build App.
- 4. In the Custom app tile, click Create app.

Application Name: MCHP-E54-getting-started Pricing Plan: Free

5. Click Create.

۲	Azure IoT Central		
≡		Build > New application	
$\hat{\omega}$	Home	New application Custom	
Ŷļ	Build	Answer a few quick questions and we'll get your app up and running.	
₽₽	My apps	About your app	
		Application name * 🕕	
		MCHP-E54-getting-started	
		URL * ()	
		mchp-e54-getting-started	.azureiotcentral.com
		Application template * (i)	V
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		Pricing plan	Р
		Free	N
		Try for 7 days with no commitment	
		5 free devices	5
		○ Standard 0	P K
		For devices sending a few messages per day	ir
		2 free devices 400 messages/mo	
			S
		○ Standard 1	Y
		For devices sending a few messages per hour	ir
		2 free devices 5,000 messages/mo	
		Standard 2 (most popular)	
		For devices sending messages every few minutes	
		2 free devices 30,000 messages/mo	
		By clicking "Create" you agree to the Subscription Agreement □ [*] and Privacy Statement □ [*] ,	. Provisions in the
		"Standard" plans require an Azure subscription, and you acknowledge that this service is lice the terms applicable to your Azure Subscription □.	nsed to you under
		Create	

- 6. Now, we need to add a device to the application, and click on the +New button that is above the All Devices section.
- 7. Enter the following:
 - a. Device Name: myMCHPE54
 - b. Device ID mymmymchpe54chpe54
- 8. Click Create.
- 9. The device will be created and listed under all devices



Devices <	+ New 🛏 Import					II 7 0
Filter templates All devices	All devices Device explorer helps	you see all your devices. Detailed i	information like device raw data he	Ips you troubleshoot. Learn more	с	
	Device name	Device ID	Device status	Device template	Organization	Simulated
	myMCHPE54	mymchpe54	Registered	Unassigned	MCHP-E54-getting-started	No

- 10. Click on myMCHPE54. This will be the view of the data coming in.
- 11. Click on Connect at the top of the bar.

Ø Connect Manage templ	ate 🗸 🕜 Manage device 🗸			
Devices > myMCHPE54 myMCHPE Last data receive Raw data Mapped aliases	54 ed: N/A Status: Registered Organi	ization: MCHP-E54-getting-started		
Timestamp ↓	Message type	Event creation time	Unmodeled data	
			No rows found	

- 12. A Device Connections group box appears. Copy the following information and paste it in a Notepad or Notepad++ temporary document. We will need this information in the next section.
 - ID scope
 - Device ID
 - Primary Key
- 13. Close the dialog when finished.

2.3 Building the Getting Started Sample App

With the application created in Azure IoT Central and the device information collected to make the connection, we are ready to build the example.

- 1. Open File Explorer and change the directory to \Azure-RTOS-MicroChip-E54\gettingstarted\Microchip\ATSAME54-XPRO.
- 2. Double-click on ATSAME54-XPRO.code-workspace to open the workspace in Visual Studio Code.
- 3. You will be asked to trust the authors of the code, click Yes.
- 4. When asked for the toolchain at the top, accept arm-gcc-cortex-m4.
- 5. Under ATSAME54-XPRO\App, open Azure_config.h and fill in the information gathered from the Azure IoT Central application, as well as, your Wi-Fi connection settings:

Constant name	Value
IOT_DPS_ID_SCOPE	ID scope value
IOT_DPS_REGISTRATION_ID	Device ID value
IOT_DEVICE_SAS_KEY	Primary key value

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7. At the bottom click on Build. It will take a few minutes, but the build should complete successfully.

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL	lake/Build ∨ ☴ 읍 🖱 ^ ×
[build] [1201/1205] Linking C static library lib\netxduo\addons\azure_iot\azure_iot_security_module\iot-security-module-core\libasc_security_core.a	
[build] [1202/1205] Linking C static library lib\netxduo\addons\azure_iot\azure_iot_security_module\libiot_security_module.a	
[build] [1203/1205] Linking C static library lib\netxduo\libnetxduo.a	
[build] [1204/1205] Linking C executable app\mxchip_azure_iot.elf	
[build] Memory region Used Size Region Size %age Used	
[build] RAM: 119328 B 128 KB 91.04%	
[build] FLASH: 625524 B 1 MB 59.65%	
[build] CCMRAM: 0 GB 64 KB 0.00%	
[build] [1205/1205] cmd.exe /C "cd /D E:\Azure-RTOS-MXCHIP\getting-started\MXChip\AZ3166\build\app && "C:\Program Files (x86)\GNU Arm Embedded Toolchain\10 2021.10\b	in\arm-none-eabi-objcopy.exe"
-Obinary mxchip_azure_iot.elf mxchip_azure_iot.bin && "C:\Program Files (x86)\GNU Arm Embedded Toolchain\10 2021.10\bin\arm-none-eabi-objcopy.exe" -Oihex mxchip_azure	e_iot.elf mxchip_azure_iot.hex"
[build] Build finished with exit code 0	
suid 🗶 [arm-gcc-contex-m4] [[Targets in Preset]] 🗘 Þ 🗶 No Test Preset Selected 🛛 🕹 Ln 36, Col 80 ,	Spaces:4 UTF-8 LF C Win32 🖗 🗯

2.4 Program the ATSAME54-XPRO Board

With the atsame54_azure_iot.bin built, programming the board is a simple copy and paste.

- 1. Make sure the board is connected to the development machine.
- 2. Open Microchip Command Prompt.
- 3. Change directory to \Azure-RTOS-MicroChip-E54\getting-started\Microchip\ATSAME54-XPRO\build\app.

Name	Date modified	Туре	Size
CMakeFiles	8/11/2022 4:14 PM	File folder	
atsame54_azure_iot.bin	8/11/2022 4:46 PM	BIN File	375 KB
atsame54_azure_iot.elf	8/11/2022 4:46 PM	ELF File	7,606 KB
atsame54_azure_iot.hex	8/11/2022 4:46 PM	HEX File	1,054 KB
🖹 cmake_install.cmake	8/11/2022 4:14 PM	CMake Source File	2 KB

4. Run the following

atprogram --tool edbg --interface SWD --device ATSAME54P20A program --chiperase --file atsame54_azure_iot.bin --verify

- 5. If asked to allow the application to go through the firewall, click Allow. Wait for the message that programming and verification have completed successfully before going to the next step.
- 6. Open a serial terminal program and connect to the COM port and set the baud rate to 115200 and enable Flow Control DTR/DSR (hardware).
- 7. Hit the reset button on the ATSAME54-XPRO.

If all goes well, you will see the terminal output with something similar to the following:

Starting Azure thread

Initializing DHCP MAC: FC:C2:3D:23:58:4B IP address: 192.168.1.239 Mask: 255.255.255.0 Gateway: 192.168.1.1 SUCCESS: DHCP initialized Initializing DNS client DNS address: 192.168.1.1 SUCCESS: DNS client initialized Copyright © 2023 Annabooks, LLC. All rights reserved Windows is a registered trademark of Microsoft Corporation All other copyrighted, registered, and trademarked material remains the property of the respective owners.

```
Initializing SNTP time sync
       SNTP server 0.pool.ntp.org
       SNTP time update: Aud 12, 2022 0:23:12.543 UTC
SUCCESS: SNTP initialized
Initializing Azure IoT DPS client
       DPS endpoint: global.azure-devices-provisioning.net
       DPS ID scope: 0ne00706F71
       Registration ID: mymchpe54
SUCCESS: Azure IoT DPS client initialized
Initializing Azure IoT Hub client
       Hub hostname: iotc-c131322c-97ad-4083-86e6-3a9776985e11.azure-devices.ne
t
       Device id: mymchpe54
       Model id: dtmi:azurertos:devkit:gsg;2
SUCCESS: Connected to IoT Hub
Receive properties: {"desired":{"$version":1},"reported":{"deviceInformation":{"
 _t":"c","manufacturer":"Microchip","model":"ATSAME54-XPRO","swVersion":"1.0.0",
urer":"Microchip","totalStorage":1024,"totalMemory":256},"ledState":false,"telem
etryInterval":{"ac":200,"av":1,"value":10},"$version":27}}
Sending property: $iothub/twin/PATCH/properties/reported/?$rid=3{"deviceInformat
ion":{"__t":"c","manufacturer":"Microchip","model":"ATSAME54-XPRO","swVersion":"
1.0.0","osName":"Azure RTOS","processorArchitecture":"Arm Cortex M4","processorM
anufacturer":"Microchip","totalStorage":1024,"totalMemory":256}}
Sending property: $iothub/twin/PATCH/properties/reported/?$rid=5{"ledState":fals
e}
Sending property: $iothub/twin/PATCH/properties/reported/?$rid=7{"telemetryInter
val":{"ac":200,"av":1,"value":10}}
```

Starting Main loop

8. In Azure IoT Central, refresh the browser to see the myMCHPE54 device. Since there is no weather station hardware connected, there is no data.



		For a consider a consider a consideration of the constant of t	ation: MCHP-E54-getting-started
t Overview Comma	nd Raw data Mapped aliases		
mperature		2	Temperature
	 Temperature 		
		•••	
]			
0.02 -			No data found
0.0 -			connection, and make sure you're part of the device's org.
-0.02 -			
	1		

- 9. Click on Command.
- 10. Set the State to False.
- 11. Click Run, and the LED on the board will turn off.
- 12. Set the State to True.
- 13. Click Run, and the LED on the board will turn on.

Devices > Getting Started Guide > myMCHPE54 myMCHPE54 Connected Last data received: 8/11/2022, 5:16:12 PM Status: Provisioned Organization: MCHP-E54-getting-started
About Overview Command Raw data Mapped aliases
Getting Started Guide / Set LED state ① State ①
False
Run To see response, please check the command history.

2.5 Debugging the Application

Now, we will step through the code to see how it works.



- 1. In Visual Studio Code, hit F5.
- 2. The binary will be downloaded and a breakpoint will be hit within main.c.

C m	ain.c	×□ ℃ ♣ ♥ ♥ ◀ ₺ = ×	
AZ31	166 > a	app > C main.c > ♀ main(void)	
49		<pre>systick_interval_set(TX_TIMER_TICKS_PER_SECOND);</pre>	
50			
51		// Create Azure thread	
52		UINT status = tx_thread_create(&azure_thread,	
53		"Azure Thread",	
54		azure_thread_entry,	
55		0,	
56		azure_thread_stack,	
57		AZURE_THREAD_STACK_SIZE,	
58		AZURE_THREAD_PRIORITY,	
59		AZURE_THREAD_PRIORITY,	
60		TX_NO_TIME_SLICE,	
61		TX_AUTO_START);	
62			
63		if (status != TX_SUCCESS)	
64		{	
65		<pre>printf("ERROR: Azure IoT thread creation failed\r\n");</pre>	
66		}	
67	}		
68			
69	in	nt main(void)	
70	{		
71		// Initialize the board	
D 72		<pre>board_init();</pre>	
73			
74		// Enter the ThreadX kernel	
/5		tx_kernei_enter();	
76			
/7		return 0;	
/8	ł		
79			

- 3. Click Step Over (F10) to move past the board initialization call.
- 4. Click Step Over (F10) and the application thread will kick off and run.
- 5. Stop the debugger (Shift+F5).

The files that comprise the core functionality of the application are:

- main.c sets up and runs the thread.
- nx_client.c creates the callback function to send telemetry and handle receive commands.
- Azure_iot_nx_client.c this file has the main loop client_run(), which connects to Azure IoT Central and handles communications between the local application and the application on Azure IoT Central.
- 6. In main.c, set a breakpoint at line 38, which is the call to azure_iot_nx_client_entry.
- 7. Also, in nx_client.c, set another breakpoint at line 147, which is the call to turn the LED on or off.
- 8. Hit F5.
- 9. When the breakpoint hits in Main.c, hit F10 twice.
- 10. The debugger will break at line 34. Hit F11 to step into the to azure_iot_nx_client_entry call.
- 11. Hit F5 to allow the code to continue.
- 12. The debugger is now in the main loop in Azure_iot_nx_client.c. In Azure IoT Central, click on Command, set the LED State to True, and click Run.

Devices >	Getting Sta	Inted Guide > 1	myMCHPE54 4 data received	d: 8/12/2022, 11:46:41 AM Status: Provisioned Org
About	Overview	Command	Raw data	Mapped aliases
Getti	ng Started	Guide / Set	LED state(D
False	2			
Ru	n			

- 13. A breakpoint should be hit at line 147 in nx_client.c.
- 14. Hit F5 to continue debugging and the LED should turn on.
- 15. Change the state of the LED a few times and watch each time the breakpoint is hit.

If you have installed the embedded tools into Visual Studio Code, you will be able to see the Peripherals and Cortex Registers in the Debug section.

$\sim c$	ALL STACK Paused on step
	command_received_cb@0x00007570 E:/Azure-RTOS-Micr
	process_command@0x000031f0 E:/Azure-RTOS-MicroChip
	client_run@0x00003fcc E:/Azure-RTOS-MicroChip-E54/
	<pre>azure_iot_nx_client_dps_run@0x00004066 E:/Azure-R</pre>
	azure_iot_nx_client_entry@0x000077ac E:/Azure-RTO
∨ B	REAKPOINTS
•	main.c app (38)
•	nx_client.c app (147)
~ 0	ORTEX PERIPHERALS
\rightarrow	AC @ 0x42002000
>	ADC0 @ 0x43001c00
>	ADC1 @ 0x43002000
>	AES @ 0x42002400
>	CAN0 @ 0x42000000
~ c	ORTEX REGISTERS
	r0 0
	r1 -1
	r2 0
	r3 0
	r4 29949
V P	EKIPTICKAL VIEW Waiting for register data from debugger
	Watting for register data nom debugget

16. Hit Shift+F5 to stop debugging.

3 Conclusion

Sample projects are good starting points to get familiar with the software. The ability to step through the code and see the API calls during operation provides good insight when documentation is lacking. The paper here covered debugging with Visual Studio Code, but further development should be done using the Microchip MPLAB tools that provide a richer development experience and direct processor support.



References

More information on the Azure IoT SDKs can be found here.

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